

In the Abstract:

Replace the original Abstract of the Disclosure, as follows:

--A vehicle control system ~~is provided for detecting the approach of another vehicle to perform a collision avoidance action. The system comprises capturing means for capturing~~ captures an external image from the primary vehicle; ~~template memory means for storing and stores~~ templates for detecting the approach of the another vehicle in order to perform a collision avoidance action.; A ~~template update means for updating~~ is updated the templates when a brake pedal is pressed by a driver; ~~recognizing means for comparing and~~ the external image is compared with the template ~~and calculating an evaluation value to determine, based upon the result of the comparison, whether the another other vehicle approaches is approaching the primary vehicle. based on the result of said comparing; and instruction means for~~ The system instructing instructs the primary vehicle to perform the collision avoidance action when ~~said evaluation value~~ the comparison exceeds a threshold value. When an image similar to the template is captured and the driver does not perform a collision avoidance action such as releasing an accelerator or pressing a brake pedal, a ~~brake system~~ throttle valve is forcibly closed. ~~Thus, the~~ to inhibit accelerator ~~becomes out of control, and sufficient~~ braking force is provided even if harsh braking is performed by the driver.--